



# **PB-SIO4A**

## **Quad Serial Port Piggyback RS422/RS485**

Manual ID 19958, Rev. Index 0300  
Sep 99



The product described in this manual is in compliance with all applied CE standards.

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# Preface

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## Revision History

Revision History			
Manual/Product Title:		PB-SIO4A	
Manual ID Number:		19958	
Rev. Index	Brief Description of Changes	Board Index	Date of Issue
A	Preliminary		Jul 1992
1	Correction to Table 2.4.1		Dec 1992
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## Explanation of Symbols



### CE Conformity

This symbol indicates that the item described in this manual is in compliance with all applied CE standards. See also the section “Applied standards” of this manual.



### Caution!

This symbol and title warn you of hazards due to electrical shocks (> 60 V) when touching products or parts of them. The non-observance of the measures indicated and/or prescribed by the law may cause harm to your product and/or life/health.

See also the section “High Voltage Safety Instructions”.



### ESD-Sensitive Device!

This symbol and title inform you that electronic boards and their components are sensitive to static electricity. Therefore, care must be taken during all handling operations and inspections of this product, in order to ensure product integrity at all times.

Please read also the section “Special Handling and Unpacking Instructions” of this manual.



### Attention!

This symbol and title emphasize aspects which, if not read through carefully by the reader, might cause hazards to health and/or damages to material.



### Note:

This symbol and title emphasize aspects the reader should read through carefully for his or her own advantage.



### PEP Advantage

This symbol and title emphasize advantages or positive aspects of a product and/or procedure.



### Troubleshooting

This symbol and title characterize a message containing useful information on troubleshooting and problem solving.



## For your safety

Your new *PEP* product was developed and tested carefully to provide all features necessary to ensure the renown electrical safety requirements. It was also designed for a long fault-free life. However, the life expectancy of your product can be drastically reduced by improper treatment during unpacking and installation. Therefore, in the interests of your own safety and of the correct operation of your new *PEP* product, you are requested to conform with the following guidelines.

### High Voltage Safety Instructions



#### **Warning!**

All operations on this device must be carried out by sufficiently skilled personnel only.



#### **Caution!**

However, serious electrical shock hazards exist during all installation, repair and maintenance operations with this product. Therefore, always unplug the power cable to avoid exposure to hazardous voltage.




Before installing your new *PEP* product into a system always ensure that your mains power is switched off. This applies also to the installation of piggybacks.

### Special Handling and Unpacking Instructions



#### **ESD Sensitive Device!**

Electronic boards and their components are sensitive to static electricity. Therefore, care must be taken during all handling operations and inspections of this product, in order to ensure product integrity at all times.

-  Do not handle this product out of its protective enclosure while it is not used for operational purposes, unless it is otherwise protected.
-  Whenever possible, unpack or pack this product only at EOS/ESD safe work stations. Where safe work stations are not guaranteed, it is important for the user to be electrically discharged before touching the product with his/her hands or tools. This is most easily done by touching a metal part of your system housing.
-  It is particularly important to observe standard anti-static precautions when changing piggybacks, ROM devices, jumper settings etc. If the product contains batteries for RTC or memory back-up, ensure that the board is not placed on conductive surfaces, including anti-static plastics or sponges. They can cause short circuits and damage the batteries or tracks on the board.



## General Instructions on Usage

- ☞ In order to maintain *PEP's* product warranty, this product must not be altered or modified in any way. Changes or modifications to the device, which are not explicitly approved by *PEP Modular Computers* and described in this manual or received from *PEP* Technical Support as a special handling instruction, will void your warranty.
- ☞ This device should only be installed in or connected to systems that fulfill all necessary technical and specific environmental requirements. This applies also to the operational temperature range of the specific board version, which must not be exceeded. If batteries are present, their temperature restrictions must be taken into account.
- ☞ In performing all necessary installation and application operations, please, follow only the instructions supplied by the present manual.
- ☞ Keep all the original packaging material for future storage or warranty shipments. If it is necessary to store or ship the board please re-pack it as nearly as possible in the manner in which it was delivered.
- ☞ Special care is necessary when handling or unpacking the product. Please, consult the special handling and unpacking instruction on the previous page of this manual.



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If the customer's eligibility for warranty has not been voided, in the event of any claim, he may return the product at the earliest possible convenience to the original place of purchase, together with a copy of the original document of purchase, a full description of the application the product is used on and a description of the defect. Pack the product in such a way as to ensure safe transportation (see our safety instructions).

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*PEP Modular Computers* will not accept liability for any further claims resulting directly or indirectly from any warranty claim, other than the above specified repair, replacement or refunding. In particular, all claims for damage to any system or process in which the product was employed, or any loss incurred as a result of the product not functioning at any given time, are excluded. The extent of *PEP Modular Computers* liability to the customer shall not exceed the original purchase price of the item for which the claim exists.

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**Chapter** **1**

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**Introduction**

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# 1. Introduction

## 1.1 Product Overview

### 1.1.1 Description

The PB-SIO4A is a quad (four) channel asynchronous RS422/RS485 serial piggyback with support for full duplex RS422/RS485 transmit, receive, and RTS/CTS handshake signals.

There are four different versions of the PB-SIO4A available:

non-optoisolated:

- RS422
- RS485

optoisolated:

- RS422
- RS485.

Any version combination can be installed on a single carrier board. Interfacing to the PB-SIO4A depends on the type of connector provided by the carrier board or optional adapters.

### 1.1.2 Features

General:

- Interrupt request line employed, interrupt vector generated by the DUART's.
- Board ID byte for remote (software) configuration identity checking.
- Compact size, four serial ports within standard industrial I/O piggyback dimensions.
- Easy to maintain. Quick and simple replacement if required.

Hardware:

- Full electrical and mechanical compatibility with the extensive range of carrier boards.
- All required VMEbus lines are available on the piggyback.
- Optional optoisolated driver/receiver supporting TxD and RxD.
- Optional interface adapters with four 15-pin D-sub connectors. (See Adapter AD-SIO4 chapter this manual)
- Extended temperature version available for harsh industrial environments.

## 1.2 Board Overview

The PB-SIO4A has two connectors for interfacing to the carrier board. Connector ST101 interfaces to the CPU side of the carrier board whereas connector ST102 provides interfacing to the external interface side of the carrier board.



This piggyback is fitted with DUART devices (two driver/receiver devices each handling two of the four serial channels), as well as a GAL device containing the specific interrupt handling logic and other features such as the I.D. number.

The optoisolated versions have eight optocouplers which are replaced with wire bridges on the non-optoisolated versions.

For operational configuration of this piggyback there are solder jumpers located both on the front and rear side of the board.

Figure 1-1: PB-SIO4A Board Front View (Optoisolated Version)

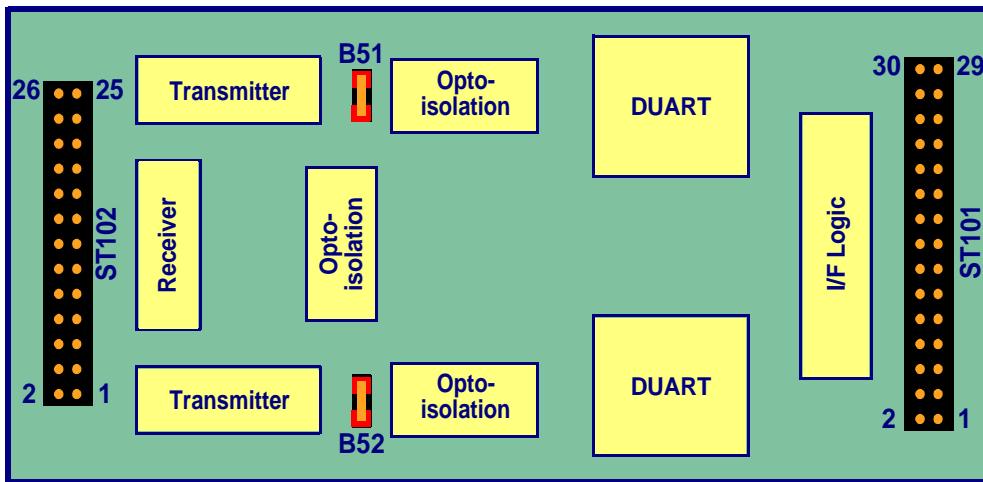
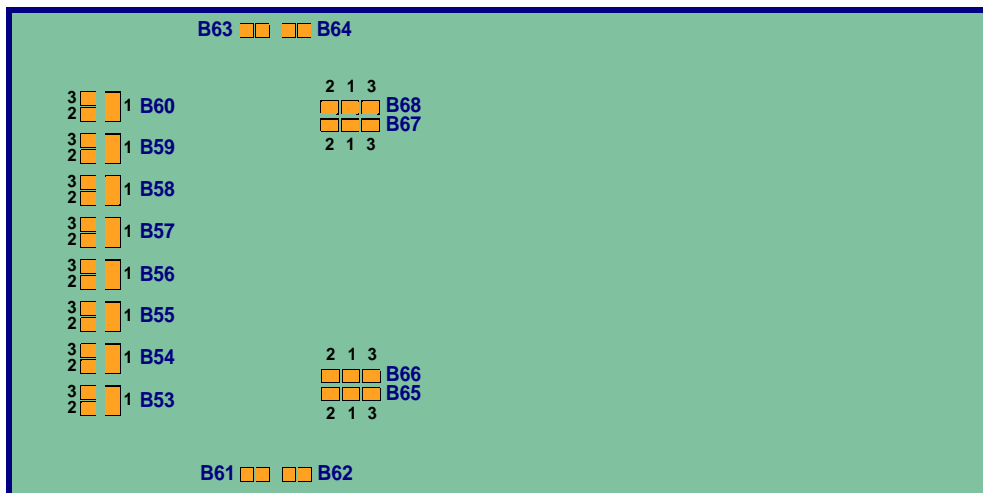


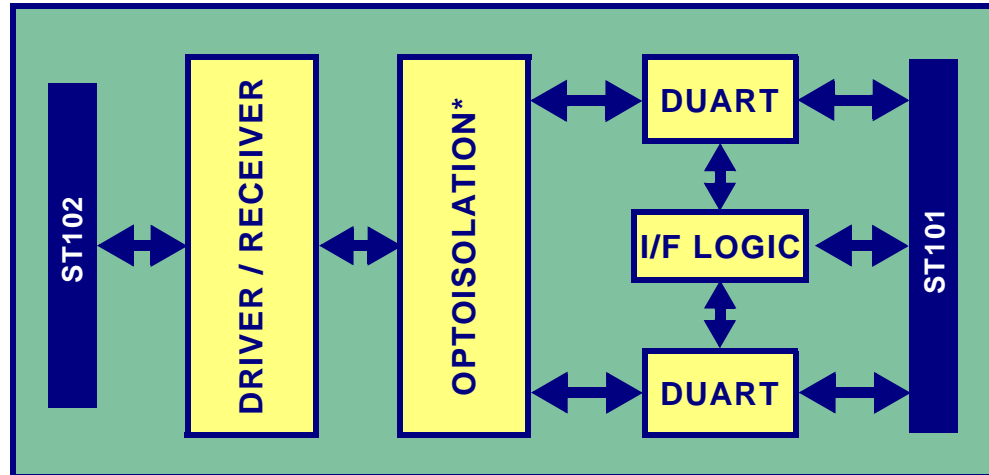
Figure 1-2: PB-SIO4A Board Rear View (Optoisolated Version)





### 1.3 Functional Block Diagram

Figure 1-3: Functional Block Diagram of the PB-SIO4A



\* Optoisolation is optional

### 1.4 PB-SIO4A External Interfacing

Connection of the PB-SIO4A piggyback to external devices is a function of the specific carrier board for the piggyback. In conjunction with the carrier board there are various possibilities for connecting the I/O channels of the piggyback to external devices.

For the carrier boards themselves there are three types of connectors available.

Front Panel:

- 50-pin male, double row, flat-ribbon cable connector, locking
- 50-pin female, Dsub connector

On-Board:

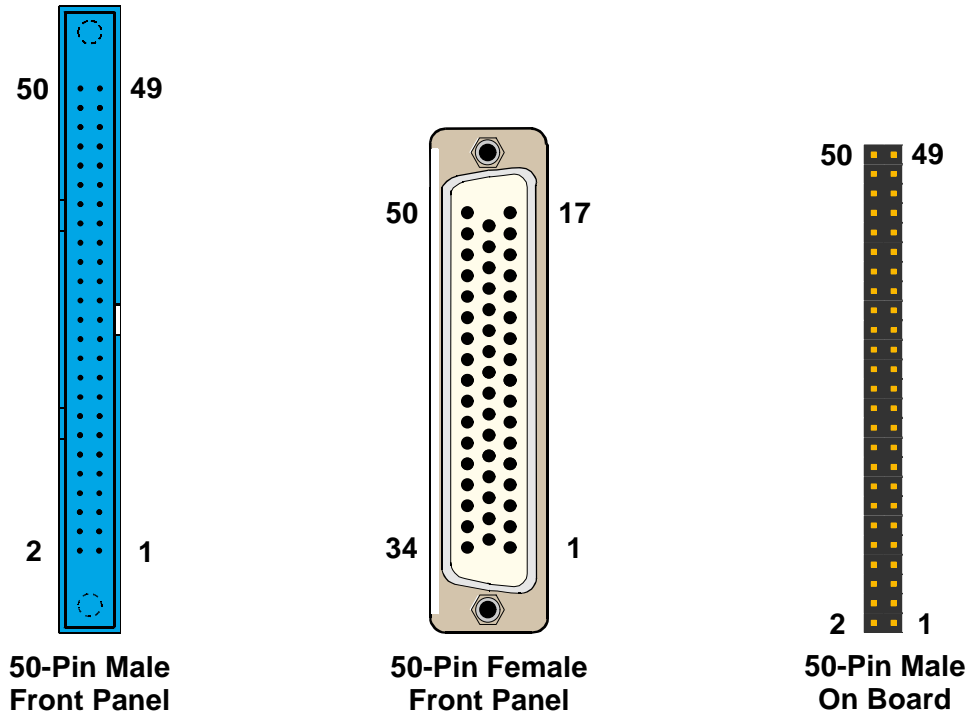
- 50-pin male, double row, flat-ribbon cable connector head

In conjunction with the carrier board's connectors, there is also the possibility of providing connection to external devices using the AD-SIO4 adapter. This adapter utilizes either of the carrier board's flat-ribbon connectors to provide 4, 15-pin female, Dsub connectors. One connector for each channel of the PB-SIO4A. Two PB-SIO4A's and two of these adapters can be combined to provide 8 serial I/O channels. The AD-SIO4 is optional and must be ordered separately. See chapter 4 of this manual for a description of the AD-SIO4.



### 1.5 Carrier Board External Connectors

Figure 1-4: Carrier Board External Connector Types





## 1.6 Technical Specifications

**Table 1-1: PB-SIO4A Technical Specification**

PB-SIO4A	Specification
Standard	RS422 or RS485
Number of Channels	four per PB-SIO4A module
Controller	two MC68681 DUART's (one pro port pair)
Transfer Rates	asynchronous: up to 115,200 Baud
Programmable Data Format	<ul style="list-style-type: none"> <li>• 5 ... 8 bit, plus parity</li> <li>• odd, even, no parity, and force parity</li> <li>• 1, 1½, and 2 stop bits</li> </ul>
Programmable Channel Modes	<ul style="list-style-type: none"> <li>• normal, full duplex</li> <li>• automatic echo</li> <li>• local loopback</li> <li>• remote loopback</li> </ul>
Counter / Timer	two 16-bit (one for each DUART)
Identification Byte	E7 hex
DTACK Generation	on board
Power Supply	5V DC, ± 5%
Power Consumption	0.4A, typical
Temperature Range	Operating: 0°C ... +70°C (Standard) -40°C ... +85°C (Extended)
Humidity	0 ... 95% non-condensing
Dimensions	Width: 48 mm (1 <sup>7</sup> / <sub>8</sub> inches) Length: 100 mm (3 <sup>15</sup> / <sub>16</sub> inches) Depth: 12 mm (1 <sup>1</sup> / <sub>2</sub> inches)
Weight	110 grams
Carrier Board Interface	two sets of twin row header pins providing all necessary communication paths and mechanical mounting



## 1.7 Applied Standards

### 1.7.1 CE Compliance

The *PEP Modular Computers*' VME products comply with the requirements of the following CE-relevant standards:

- Emission EN50081-1
- Immission EN50082-2
- Electrical Safety EN60950

### 1.7.2 Mechanical Compliance

- Mechanical Dimensions IEEE 1101.10

### 1.7.3 Environmental Tests

- Vibration/Broad-Band IEC68-2-6
- Random Vibration IEC68-2-64 (3U boards)
- Permanent Shock IEC68-2-29
- Single Shock IEC68-2-27

## 1.8 Related Publications

### 1.8.1 General

- VMEbus Specification, Revision C.1
- The MC68681 data sheet from Motorola

### 1.8.2 PEP Modular Computers

Please contact PEP Modular Computers concerning the following product manuals.

- VMOD2
- VMOD2D
- VMOD4D
- IMOD
- V642
- V662



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*Chapter* **2**

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*Installation*

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## 2. Installation

### 2.1 Board Installation



#### **Caution!**

Switch off all power to the system and ensure that there are **NO** external cables connected to the carrier board or to any optional adapters connected to the carrier board before installing the PB-SIO4A. Failure to do so could endanger your life/health and may damage your board or system.



#### **ESD Equipment!**

Your PB-SIO4A board contains electrostatically sensitive devices. Please observe the necessary precautions to avoid damage to your board:

- Discharge your clothing before touching the assembly. Tools must be discharged before use.
- Do not touch components, connector-pins or traces.
- If working at an anti-static workbench with professional discharging equipment, please do not omit to use it.



#### **Note!**

The PB-SIO4A can be installed in any free carrier board position, and can be combined with any other type of piggyback module on a carrier board. The only restraint here being the external interfacing requirements, in particular, what type of cable connection is required. It is the responsibility of the system integrator to ensure proper external interfacing to the PB-SIO4A.

To install a PB-SIO4A piggyback proceed as follows:

- ensure that the safety requirements indicated above are observed
- as required, ensure that the piggyback and carrier board are properly configured (see appropriate documentation for configuration)
- if required, remove the carrier board and optional adapters from the system
- ensure the proper orientation of the PB-SIO4A to the carrier board before installing (see appropriate documentation for orientation)
- press the piggyback onto the carrier board until fully seated



#### **Note!**

The PB-SIO4A can be securely mounted to the carrier board via screws and stand offs as appropriate



- if required, repeat this process for a second piggyback on this carrier board
- install the carrier board and optional adapters as required
- connect external interfacing cables to the carrier board and optional adapters as required
- ensure that the carrier board, optional adapters, and interfacing cables are properly secured

## **2.2 Software Installation**

### **2.2.1 Driver Installation**

Drivers are available for various operating systems but are not delivered with the PB-SIO4A. If required, please order the appropriate driver separately.

For installation of any required driver, please refer to the driver documentation itself.



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*Chapter* **3**

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*Configuration*

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## 3. Configuration

### 3.1 PB-SIO4A Address Map and ID Byte

The PB-SIO4A is addressed (odd byte access) by using the carrier board base address and one of the following offsets for the piggyback location:

Piggyback location A ( the upper position on the carrier board)

Base Address + \$01	DUART1
Base Address + \$21	DUART2
Base Address + \$41	ID Byte

Piggyback location B ( the lower position on the carrier board)

Base Address + \$81	DUART1
Base Address + \$A1	DUART2
Base Address + \$C1	ID Byte

The PB-SIO4A has an ID Byte of \$E7 (RS422/RS485).

### 3.2 VMEbus Interrupts

Each DUART device is able to issue an interrupt request (\*IRQ) to the carrier board. In the event of simultaneous interrupt requests those from DUART #1 have priority over those from DUART #2.

The interrupt level is set by the carrier board. See the carrier board documentation for setting of the level. The interrupt vector itself is provided by the DUART.

### 3.3 Jumper Settings

The jumper positions B53 to B69 are located on the rear side of the PB-SIO4A and are solder bridges. Jumpers B51 and B52 are located on the front side of the PB-SIO4A and if installed are wire bridges. They are set at the factory as required and should not be changed.



#### Note!

Before operating the PB-SIO4A ensure that the B51 and B52 jumper settings are set correctly according to the application. No external VCCext may be applied to the non-optocoupler version, and, correspondingly, external VCCext must be applied to optocoupler versions.

Table 3-1: PB-SIO4A Jumper Settings

Jumper/Channel		Setting	Default	Function
B53	A	2-3	X	receiver and driver line connected pull-up resistor for driver line pull-up resistor for receiver line pull-up resistor for driver and receiver line
B55	B	1-2		
B57	C	1-3		
B59	D	1-2-3		
B54	A	2-3	X	receiver* and driver* line connected pull-down resistor for driver* line pull-down resistor for receiver* line
B56	B	1-2		
B58	C	1-3		
B60	D			
B61	D	closed open	X	150 ohm termination resistor connected 150 ohm termination resistor not connected
B62	A			
B63	B			
B64	C			
B65	C	1-2	X	receiver control by driver enabled receiver control permanent enabled
B66	D	1-3		
B67	A			
B68	B			
B51 and B52		closed	*	VCCext and GNDext from piggyback * (This is the operational configuration when optocouplers <b>are not</b> installed.)
		open	**	VCCext and GNDext from external source ** (This is the operational configuration when optocouplers <b>are</b> installed.)



## 3.4 Pinouts

### 3.4.1 PB-SIO4A/Carrier Board Connector ST101

This is a thirty pin, dual row male header connector which provides interfacing between the PB-SIO4A and CPU side of the carrier board.

**Table 3-2: Pinout of Connector ST101**

Signal	Pin	Pin	Signal
+5V (Vcc)	30	29	GND
IA1	28	27	ID0
IA2	26	25	ID1
IA3	24	23	ID2
IA4	22	21	ID3
IA5	20	19	ID4
IA6	18	17	ID5
$\overline{IAS}$	16	15	ID6
$\overline{IDS0}$	14	13	ID7
N/C	12	11	$\overline{INT}$
$\overline{CS}$	10	9	$\overline{INTA}$
$\overline{DTACK}$	8	7	$\overline{RESET}$
CLK	6	5	$\overline{R/W}$
-12V	4	3	+12V
+5V (Vcc)	2	1	GND



### 3.4.2 PB-SIO4A/Carrier Board Connector ST102

This is a twenty-six pin, dual row male header connector which provides interfacing between the PB-SIO4A and the application side of the carrier board.

**Table 3-3: Pinout of Connector ST102**

Signal	Pin	Pin	Signal
+RxD D	26	25	+RxD D
GndE	24	23	-TxD A
+TxD A	22	21	VccE
+RxD A	20	19	-RxD A
GndE	18	17	-TxD B
+TxD B	16	15	VccE
+RxD B	14	13	-RxD B
GndE	12	11	-TxD C
+TxD C	10	9	VccE
+RxD C	8	7	-RxD C
GndE	6	5	-TxD D
+TxD D	4	3	VccE
-RxD D	2	1	-RxD D



3.4.3 PB-SIO4A to Carrier Board to AD-SIO4

Table 3-4: PB-SIO4A to Carrier Board to AD-SIO4 Pinout Table (Both Positions)

POS./DUART		Signal	ST102	Carrier Board		AD-SIO4 BU6	AD-SIO4 Front Panel		
P	D						PINS	CON/CH	
U P P E R	2	-RxD D	1, 2	50		24	11	BU4	D
		+RxD D	25,26		49	23	10		
		VccE	3	48		22	15		
		+TxD D	4		47	21	8		
		-TxD D	5	46		20	9		
		GndE	6		45	19	1,7		
	2	-RxD C	7	44		18	11	BU3	C
		+RxD C	8		43	17	10		
		VccE	9	42		16	15		
		+TxD C	10		41	15	8		
		-TxD C	11	40		14	9		
		GndE	12		39	13	1,7		
	1	-RxD B	13	38		12	11	BU2	B
		+RxD B	14		37	11	10		
		VccE	15	36		10	15		
		+TxD B	16		35	9	8		
		-TxD B	17	34		8	9		
		GndE	18		33	7	1,7		
1	-RxD A	19	32		6	11	BU1	A	
	+RxD A	20		31	5	10			
	VccE	21	30		4	15			
	+TxD A	22		29	3	8			
	-TxD A	23	28		2	9			
	GndE	24		27	1	1,7			
				26	not used				
				25	not used				



Table 3-4: PB-SIO4A to Carrier Board to AD-SIO4 Pinout Table (Both Positions)

POS./DUART		Signal	ST102	Carrier Board		AD-SIO4 BU6	AD-SIO4 Front Panel		
P	D						PINS	CON/CH	
L O W E R	2	-RxD D	1, 2	24		24	11	BU4 D	
		+RxD D	25,26		23	23	10		
		VccE	3	22		22	15		
		+TxD D	4		21	21	8		
		-TxD D	5	20		20	9		
		GndE	6		19	19	1,7		
	2	-RxD C	7	18			18	11	BU3 C
		+RxD C	8		17	17	10		
		VccE	9	16		16	15		
		+TxD C	10		15	15	8		
		-TxD C	11	14		14	9		
		GndE	12		13	13	1,7		
	1	1	-RxD B	13	12		12	11	BU2 B
			+RxD B	14		11	11	10	
			VccE	15	10		10	15	
			+TxD B	16		9	9	8	
			-TxD B	17	8		8	9	
			GndE	18		7	7	1,7	
1		-RxD A	19	6			6	11	BU1 A
		+RxD A	20		5	5	10		
		VccE	21	4		4	15		
		+TxD A	22		3	3	8		
		-TxD A	23	2		2	9		
		GndE	24		1	1	1,7		

Legend: POS(ition)/DUART, P, D; CON/CH

where: P = position on carrier board  
 D = DUART  
 CON = connector  
 CH = channel



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*Chapter* **4**

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*Adapter AD-SIO4*

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## 4. Adapter AD-SIO4

### 4.1 Product Overview

The AD-SIO4 is a special adapter designed to provide front panel connection to the PB-SIO4A using 15-pin Dsub connectors as opposed to the 50-pin connector provided by the carrier board.

This adapter consists of a separate, 8 HP front panel with four, 15-pin female Dsub connectors mounted on the front side for external device connection, and two, 24-pin, male dual row connectors for internal connection to the PB-SIO4A carrier board. Connection from the carrier board to the adapter is done via a 50-way, flat band cable with a 50-pin dual row female connector for the carrier board, and two, 24-pin dual row female connectors for connection to the adapter. This cable allows for the connection of two PB-SIO4A's to two AD-SIO4's where pins 25 and 26 are not used. See Table 3-4 for the pinout of this cable.

### 4.2 Adapter Overview

Figure 4-1: Front View of the AD-SIO4 with Dsub Pin Layout

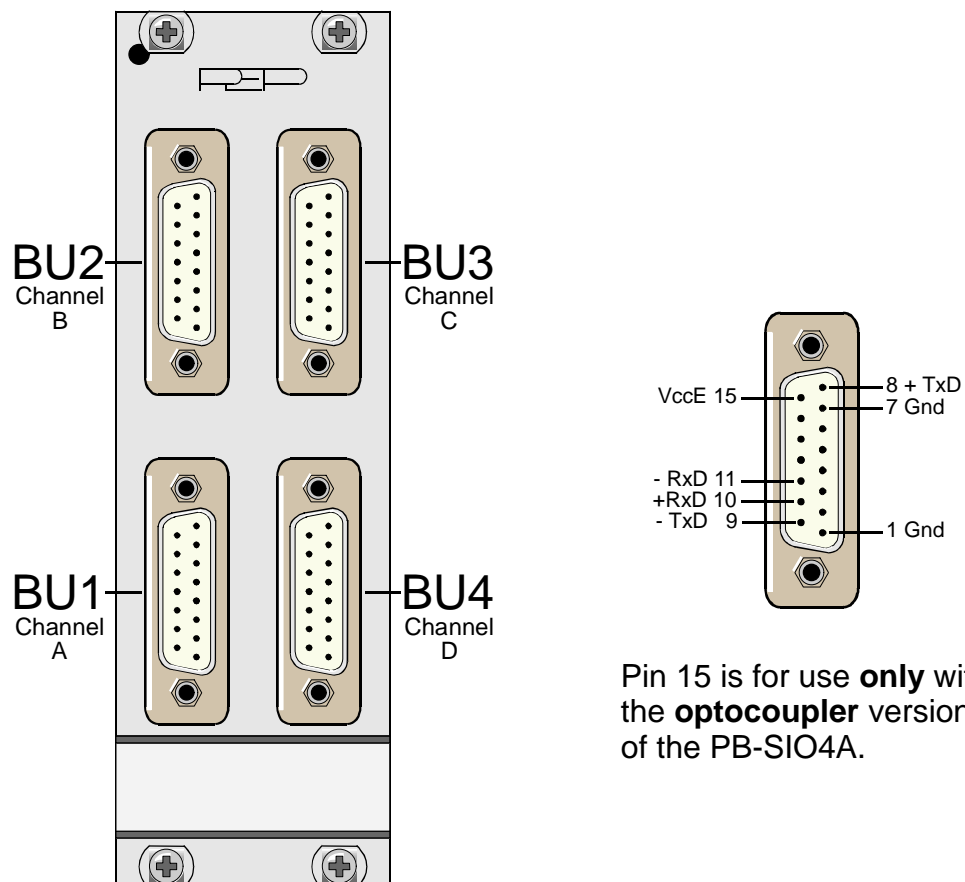
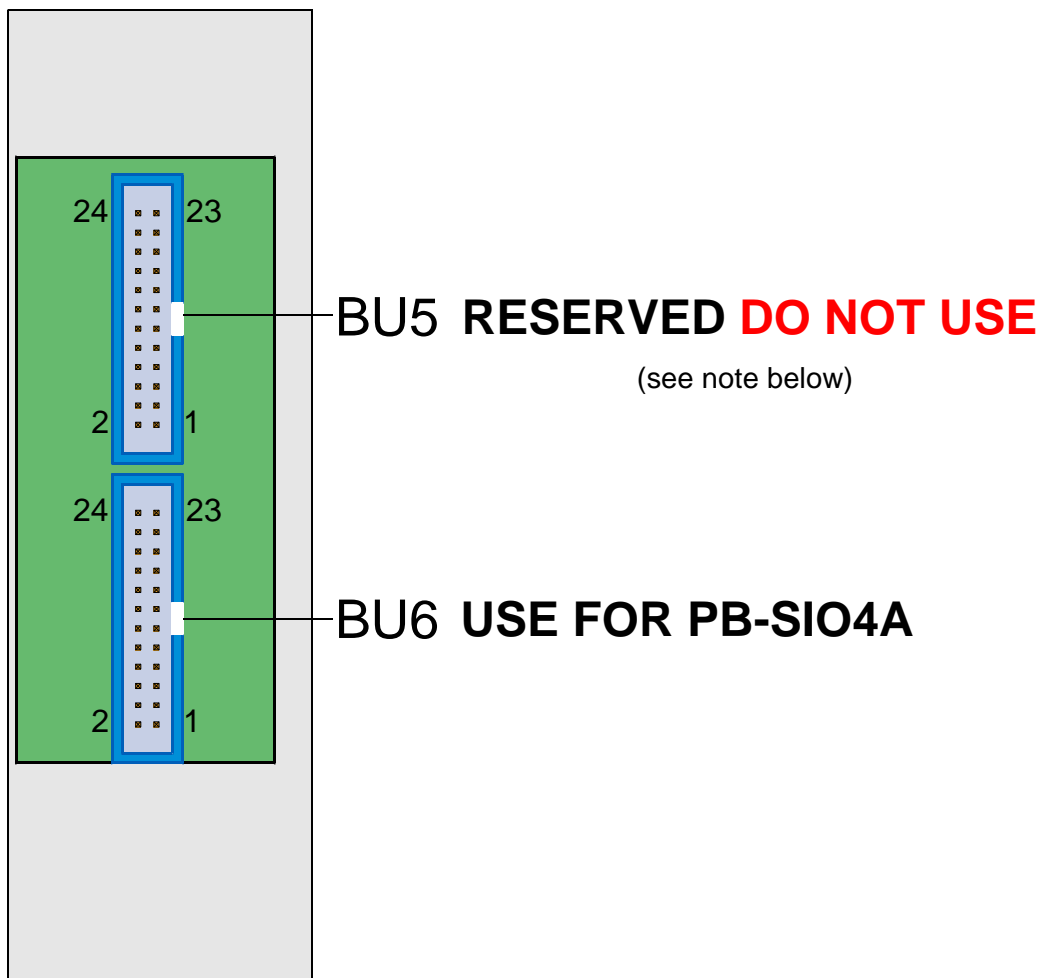




Figure 4-2: Rear View of the AD-SIO4



Connector BU6 is for use with the PB-SIO4A. Connector BU5 is reserved for use with the PB-SIO4, another serial interface piggyback from PEP.

**Note!**

Always ensure that the correct connector of the adapter cable is connected to BU6. See Table 3-4 for cable pinout.

**Note!**

For use with the PB-SIO4A ensure that there is no cable connected to BU5. Failure to comply with this will result in malfunctioning and possible damage to equipment.